

International Workshop on
Dynamic Stability Challenges of the Future Power Grids

Digital Intelligence for Modern Power Systems: Experiences in Monitoring, Modeling, Analytics, and Control of the Ecuadorian Power Grid

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From synchrophasor data to secure system operation

- Ecuadorian power system context
- WAMS infrastructure and operational applications
- Dynamic operational challenges in the Ecuadorian power system
- Oscillatory stability and PSS tuning
- Model Validation
- Real-time simulation and Digital Twins
- Predictive analytics for real-time operation
- Conclusions: Operational impact and lessons learned



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Ecuadorian Power System: A hydro-dominant grid operates through a critical regional interconnection

7,788.99 MW

2025 effective
installed
capacity

73.61%

2025 hydro
generation

5,634.31 MW

July 15, 2026

historical
domestic peak

97.81%

2025 electricity
access

Ecuador SNI

Hydroelectric
generation centers
230 / 500 kV
backbone

Four 230 kV lines

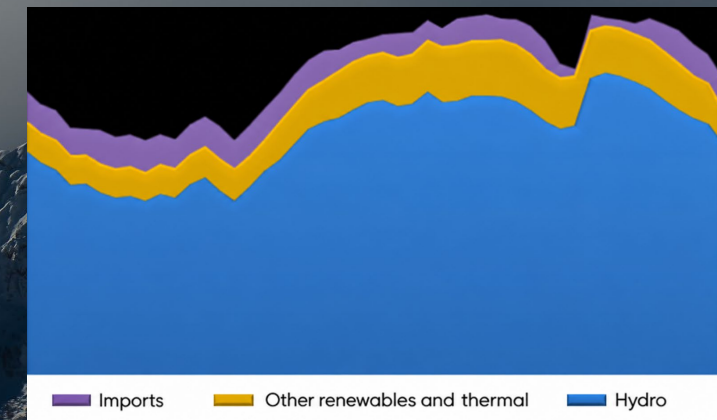
Colombia

Larger (~3 times)
synchronous
power system

Operating implication

Excitation of a persistent 0.3–
0.4 Hz inter-area mode.

Congested transmission
corridors

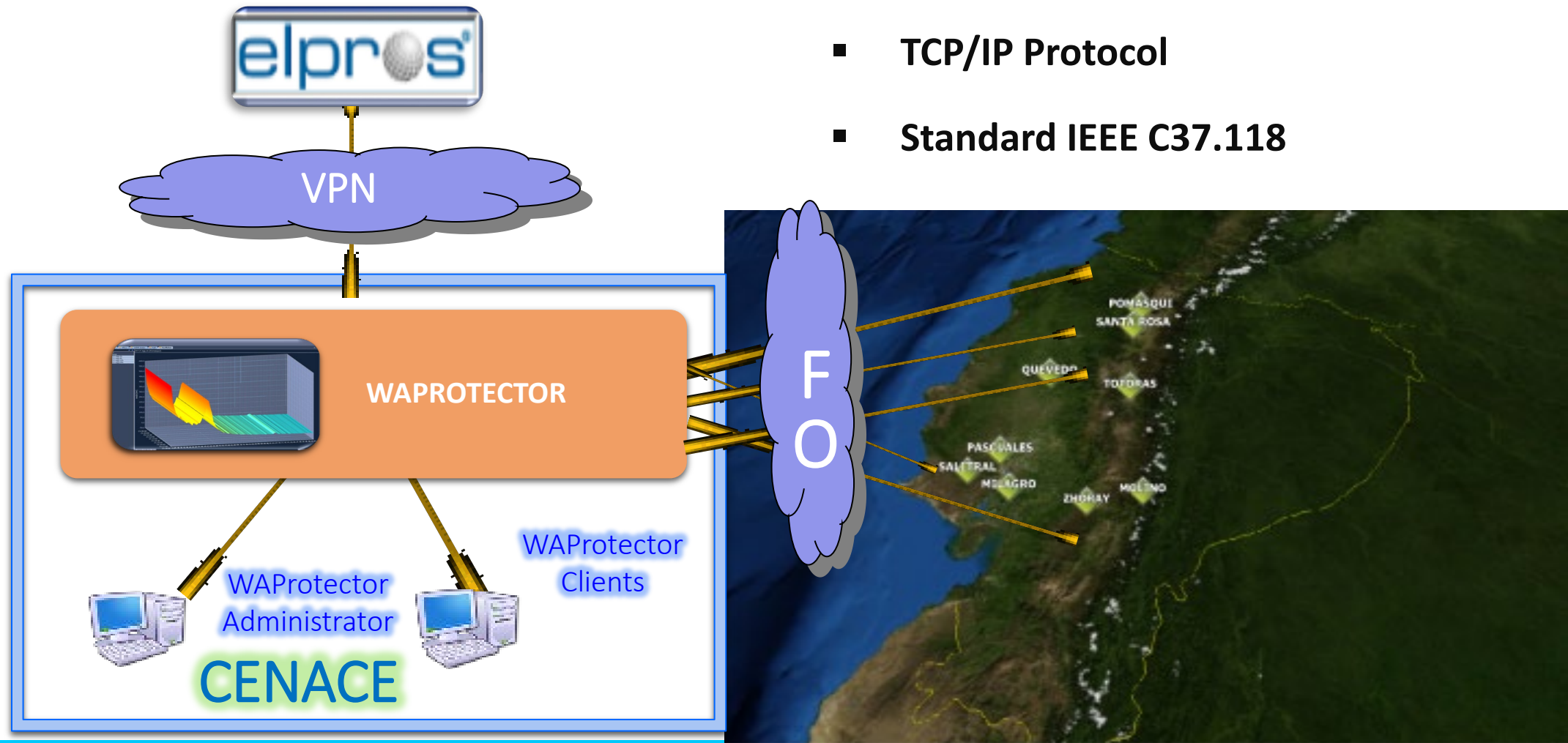


Since 2010, CENACE has built an end-to-end synchrophasor platform



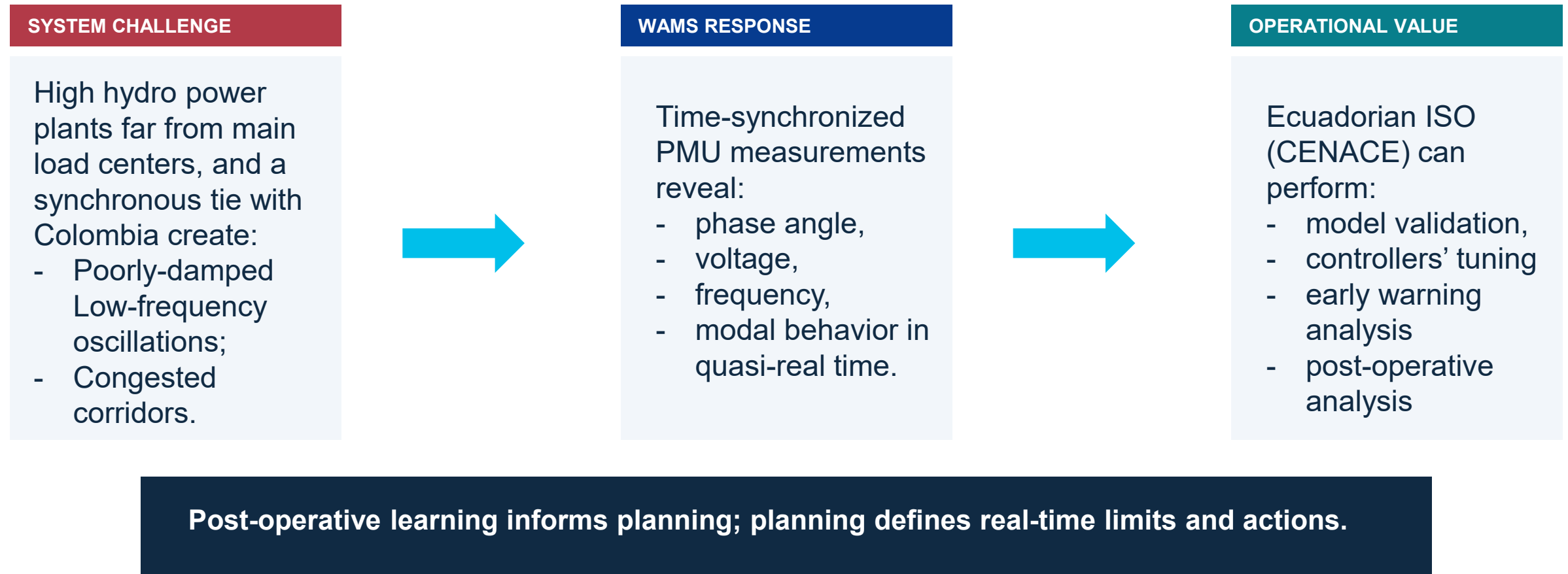
A single operational data backbone supports planning studies, real-time situational awareness and post-event analysis.

Ecuadorian WAMS

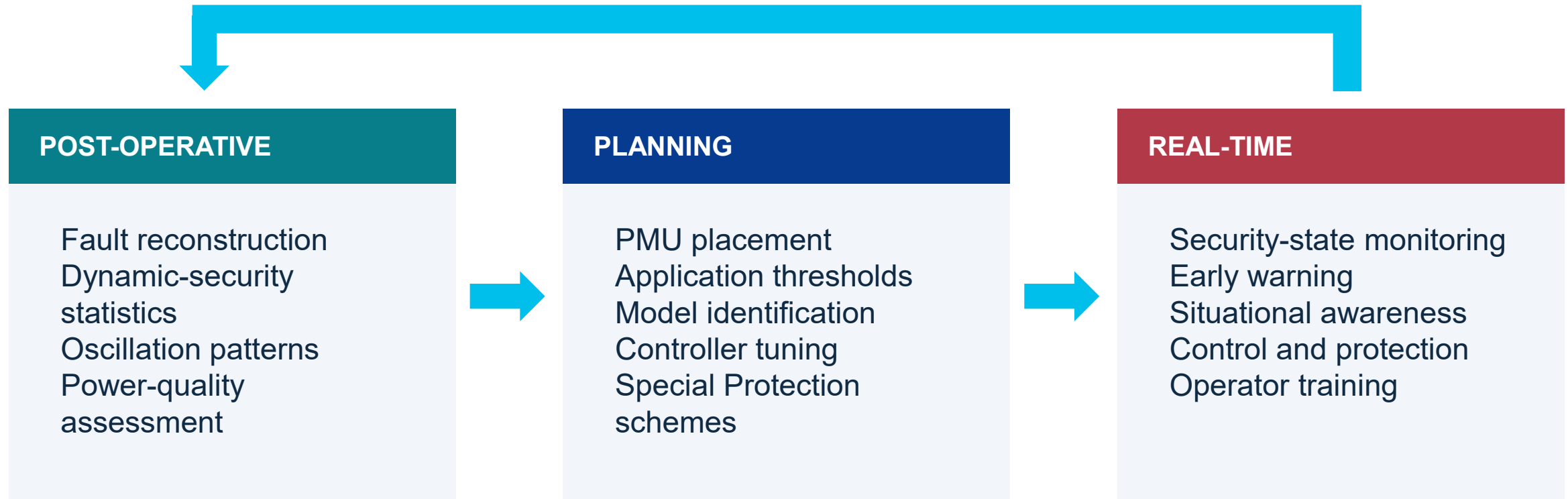


- TCP/IP Protocol
- Standard IEEE C37.118

Ecuadorian necessity of dynamic visibility beyond conventional SCADA

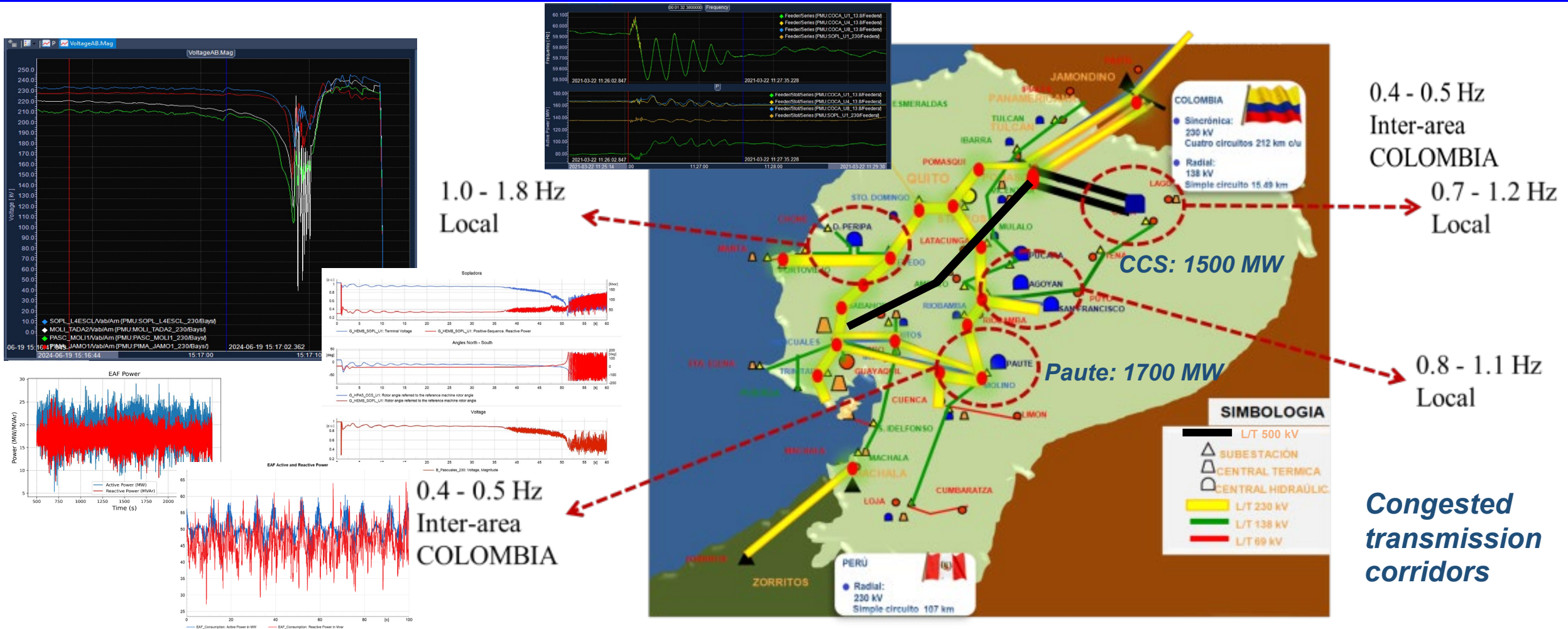


WAMS value compounds through a closed learning loop

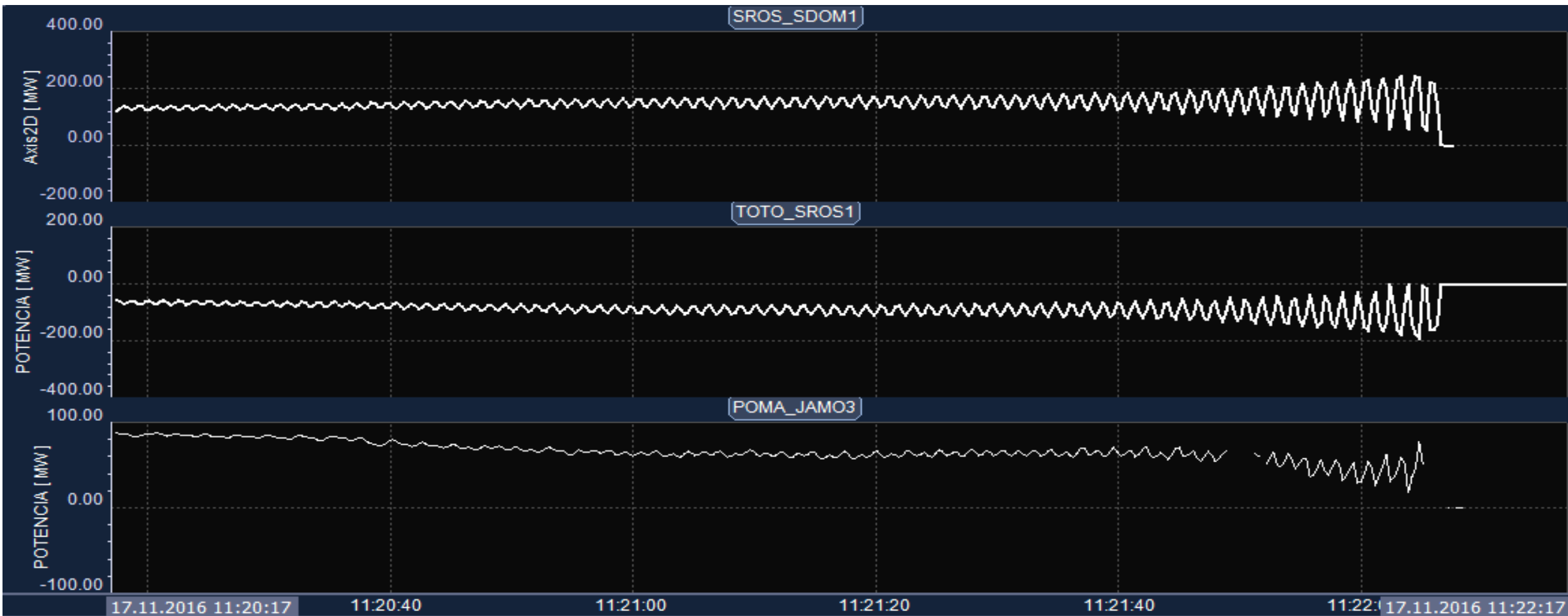


Measured behavior → validated knowledge → operating limits and actions → new records

Dynamic operational challenges in the Ecuadorian power system



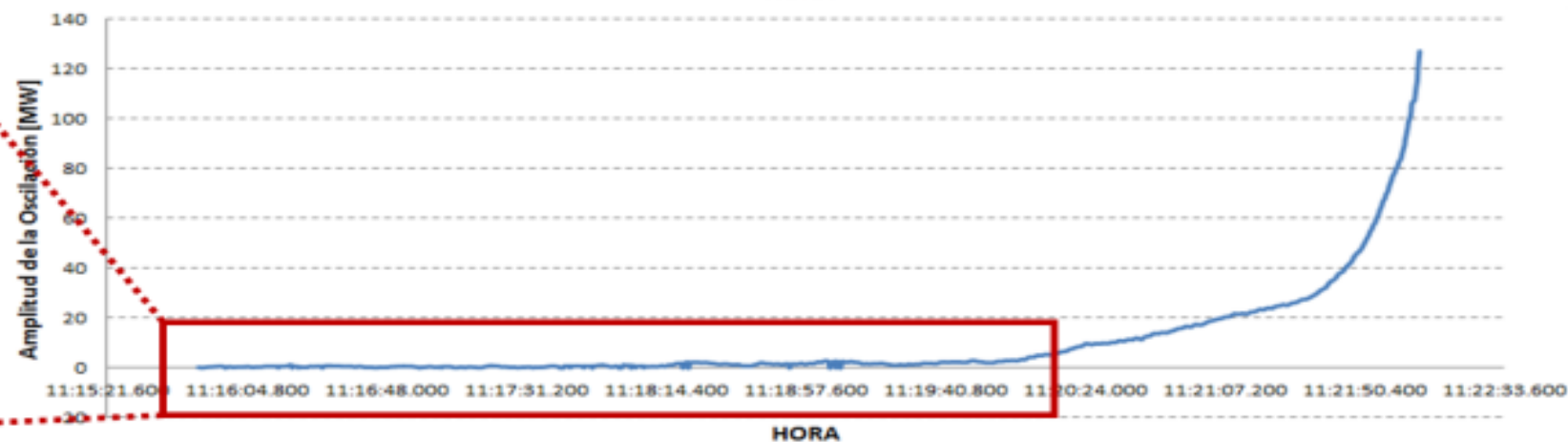
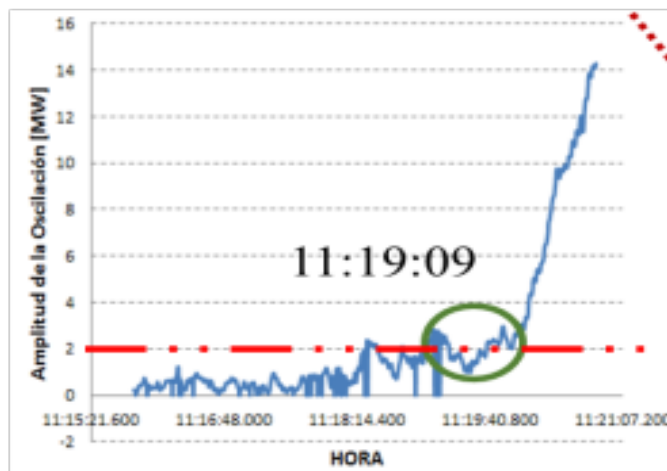
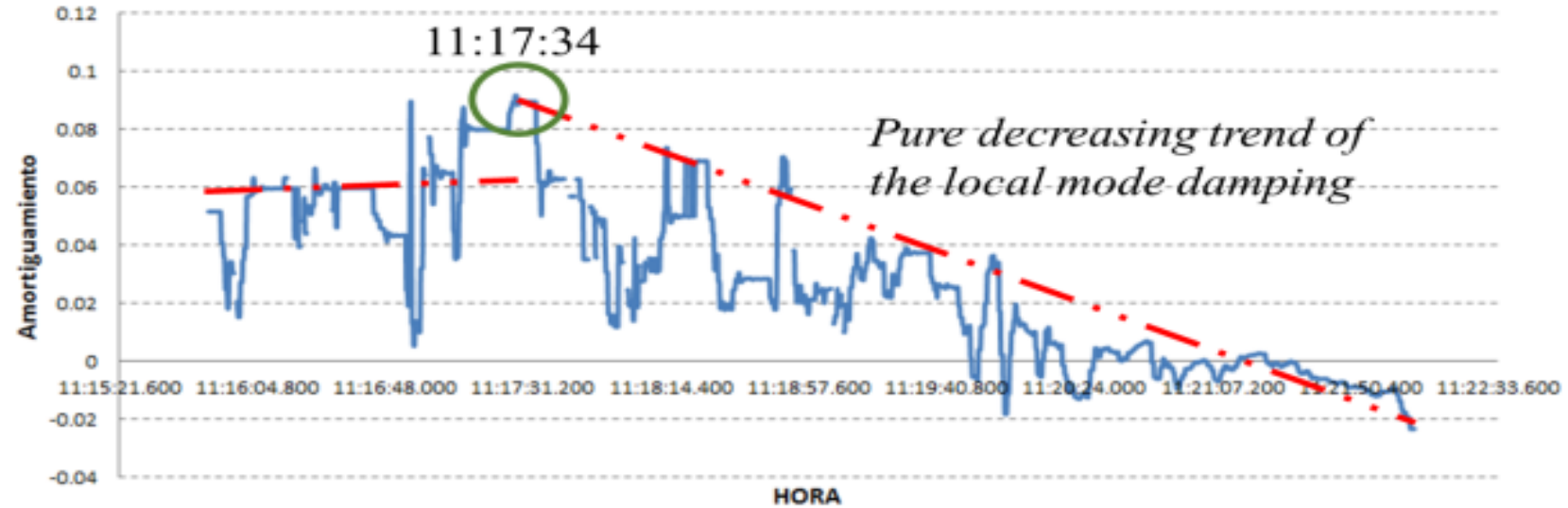
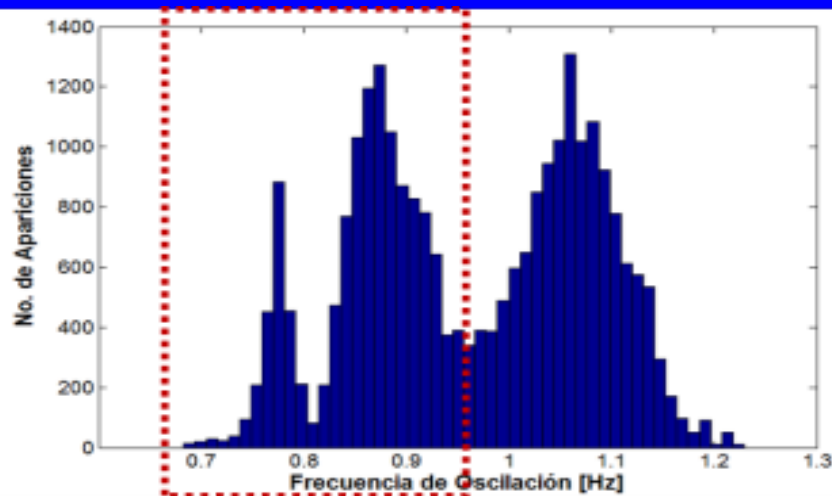
Power Flow: T/L Sta. Rosa – Sto. Domingo, T/L Totoras – Sta. Rosa and T/L Pomasqui – Jamondino



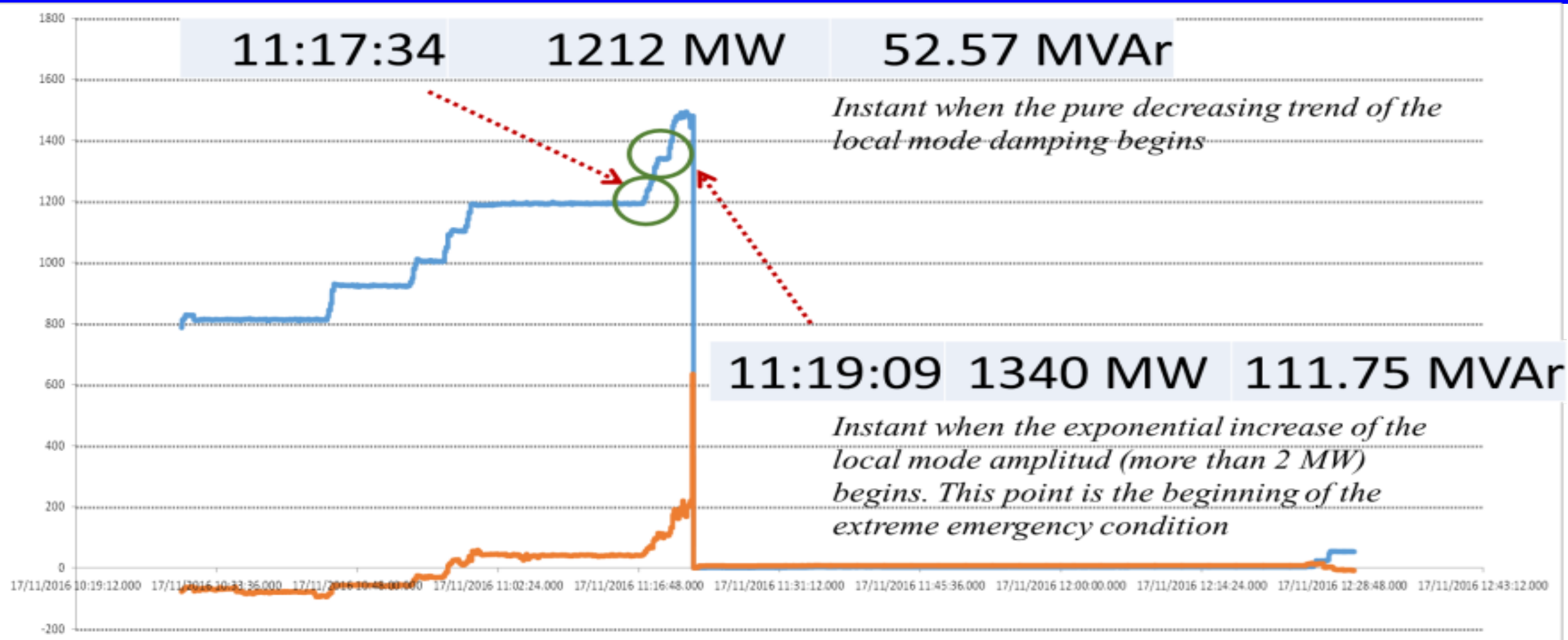
Local Oscillation mode at CCS: 0.75 Hz with negative damping



Oscillatory Local Modes: T/L Santa Rosa – Santo Domingo



Active and Reactive injection power of Coca Codo Sinclair



Local mode Oscillatory Stability Condition

The causes of the excitation of the local oscillatory mode with negative damping were:

Highly congested branches: This congestion is produced by the 230 kV system, which must withstand the high power flow from the north.

High power injections from CCS: CCS power plant is a source that injects a large amount of power (up to 1500 MW) into the Ecuadorian system, via a radial 500 kV corridor that is then connected to the 230 kV system that becomes congested.

Dynamic of power plant elements: Dynamic parameters of each one of the 8 units, and the controllers' behavior (AVR and PSS with prior parameters) also contributed to lack of damping torque.

PSS Tuning Methodology

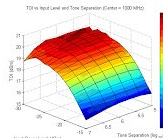


Installation of monitoring devices in the Generation power Plant: PMUs



Modeling of key system elements: generator, AVR and simplified network.

Model validation through field tests and real-time records (WAProtector)



Probabilistic Oscillatory analysis:
Modal Analysis
Frequency response
Time domain Simulation
Multiple scenarios (Monte Carlo)

PSS Tuning.- Robust Methodology:

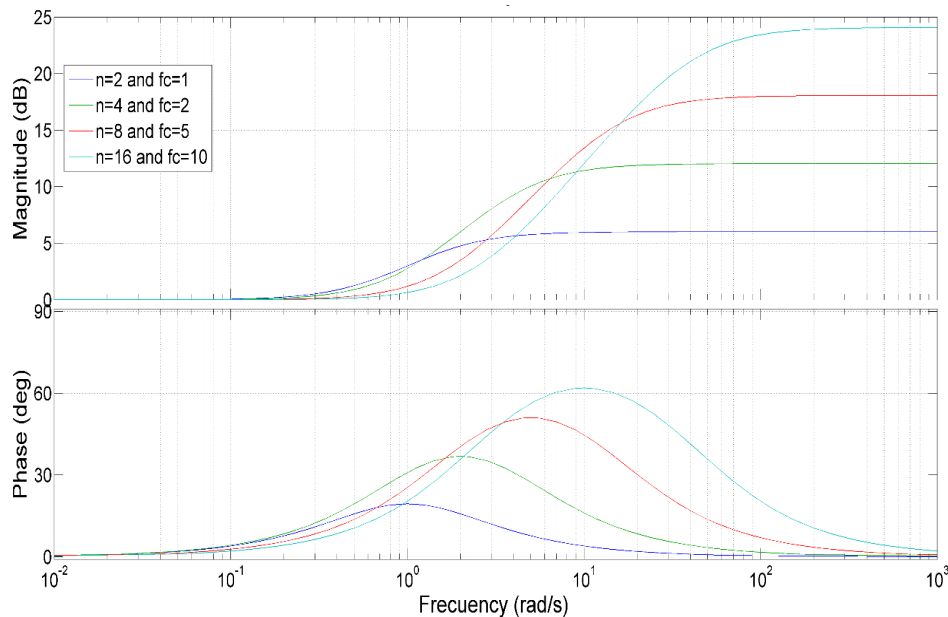
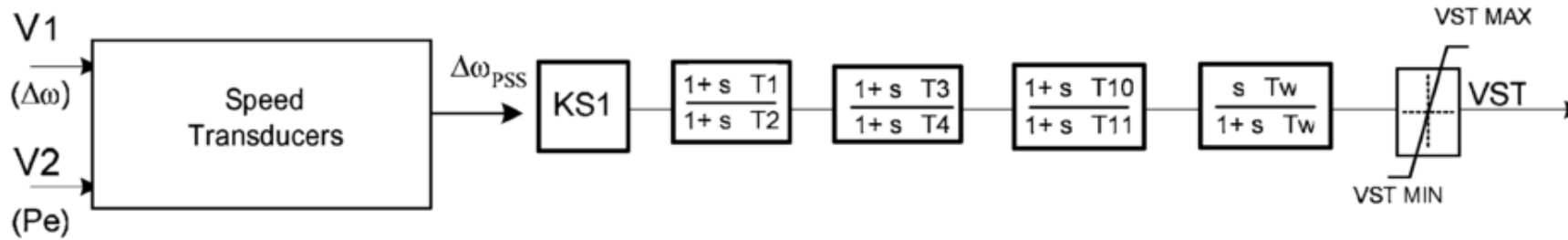
- Multiple scenarios (Monte Carlo)
- Heuristic optimization algorithm
- Frequency response (constraints)
- TestBed for PSS Tuning → *Digital Twin*

Field PSS tuning
Tuning validation tests
(WAProtector)



eMEGAsim

PSS Tuning Methodology

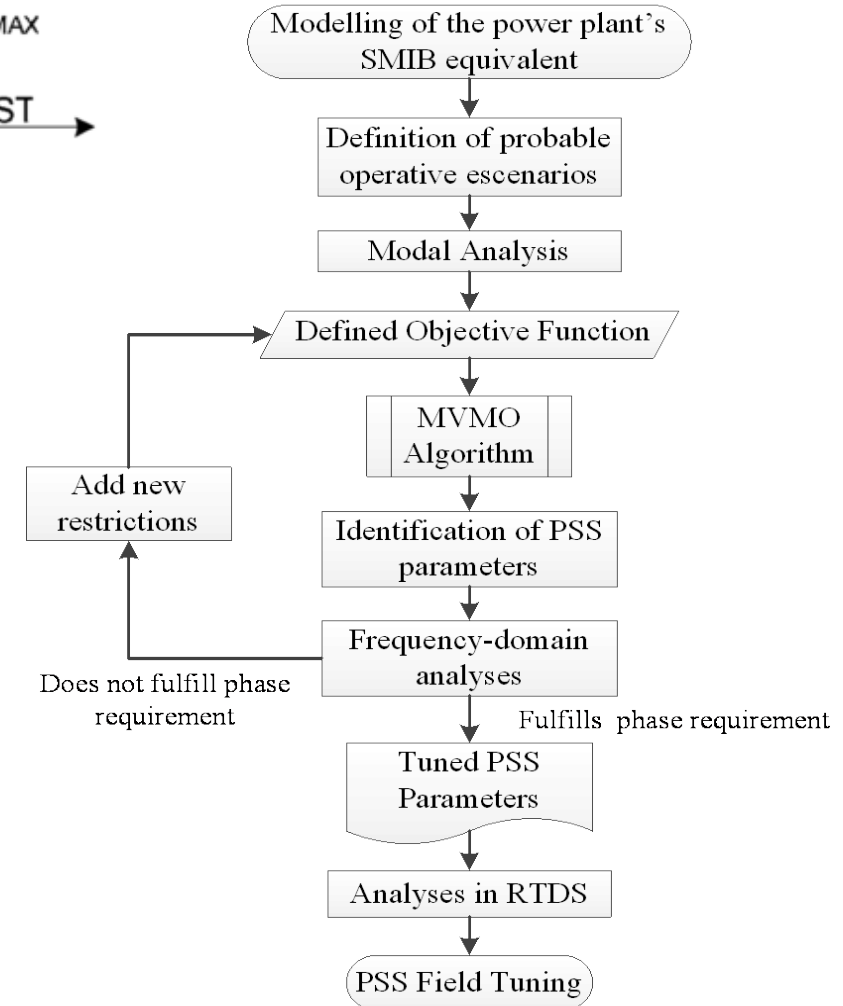


$$\min OF = |\xi_{th} - \xi_{sys}|$$

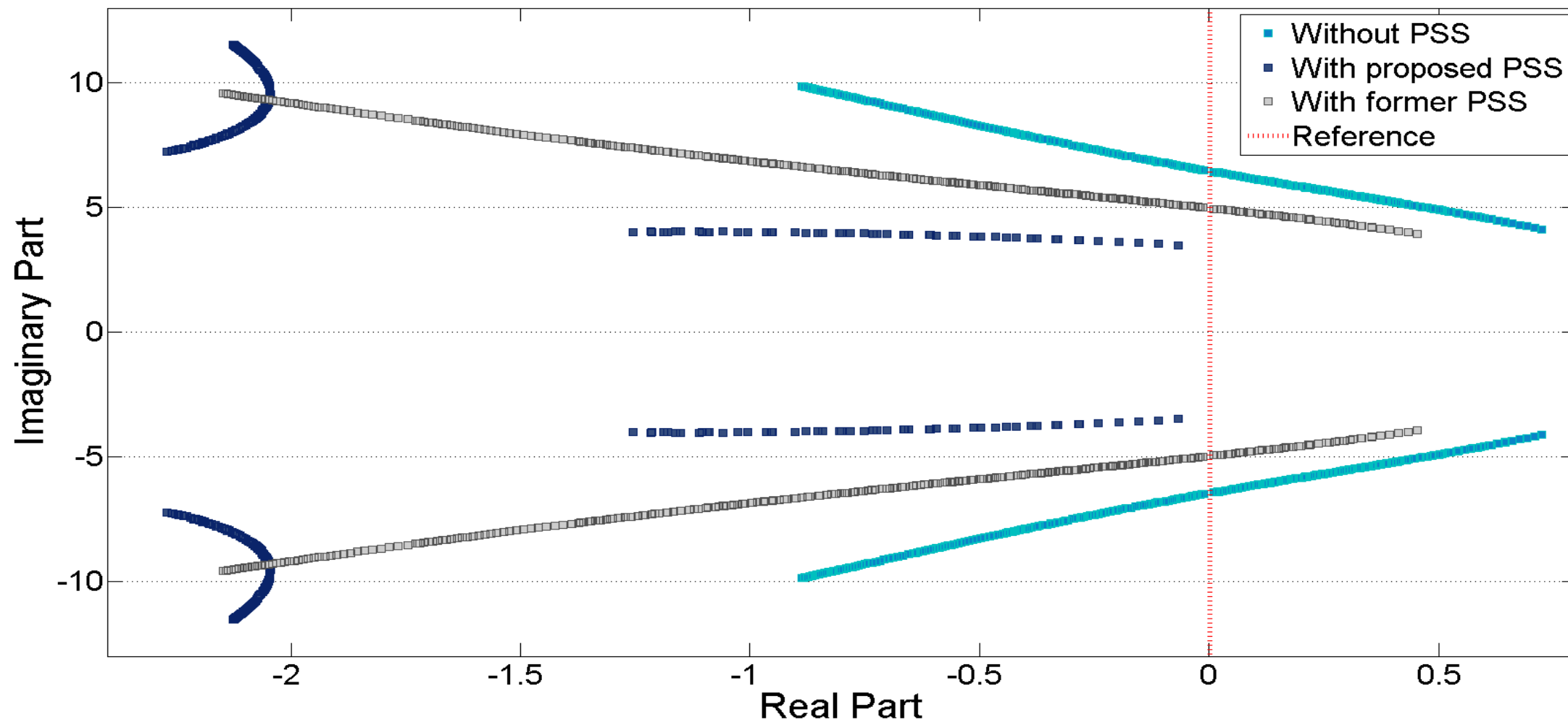
$$\xi_{sys} = \min_{p=1 \dots nm} (\xi_p)$$

$$\mathbf{x}_{j-\min} \leq \mathbf{x}_j \leq \mathbf{x}_{j-\max}$$

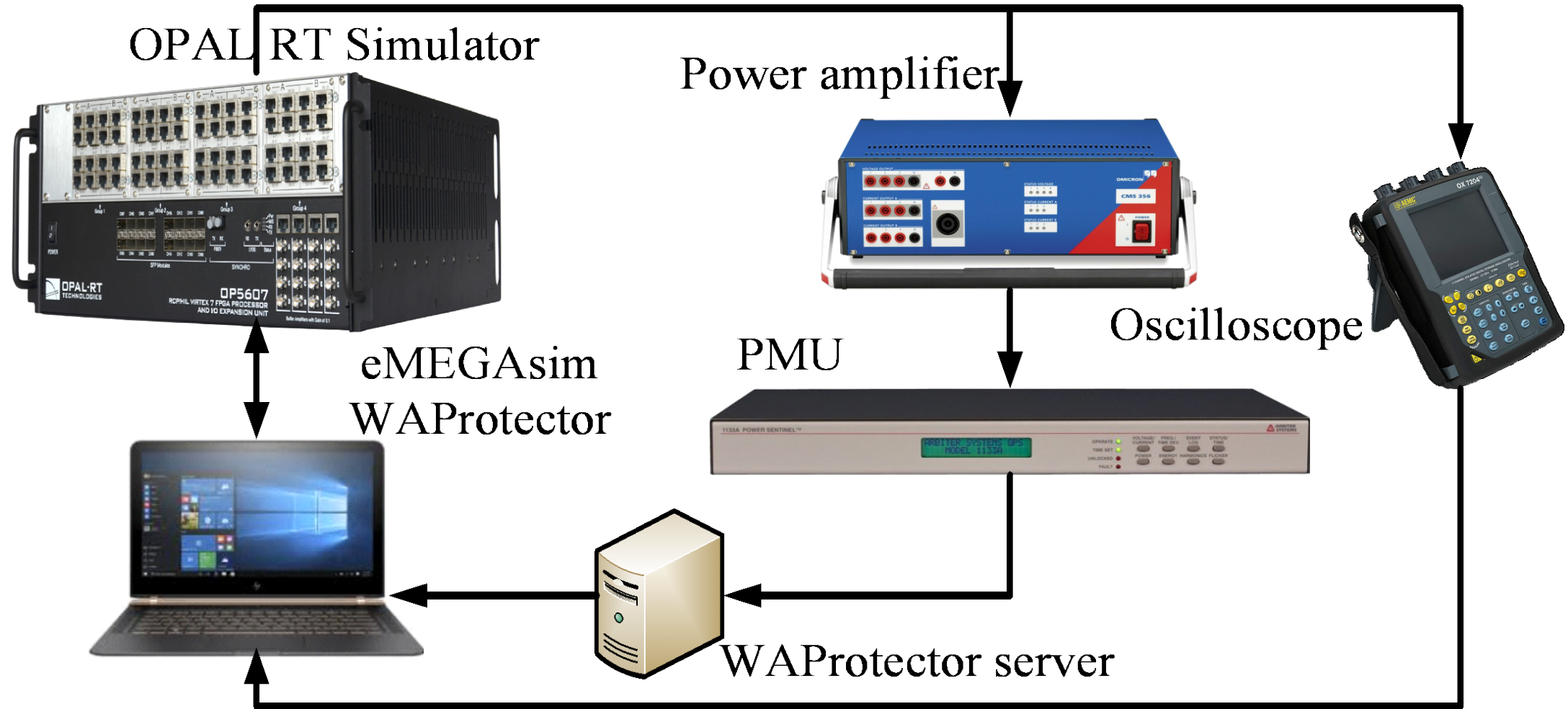
$$fc = \frac{1}{2\pi} \frac{1}{\sqrt{T_1 T_2}} \quad n = \frac{T_1}{T_2}$$



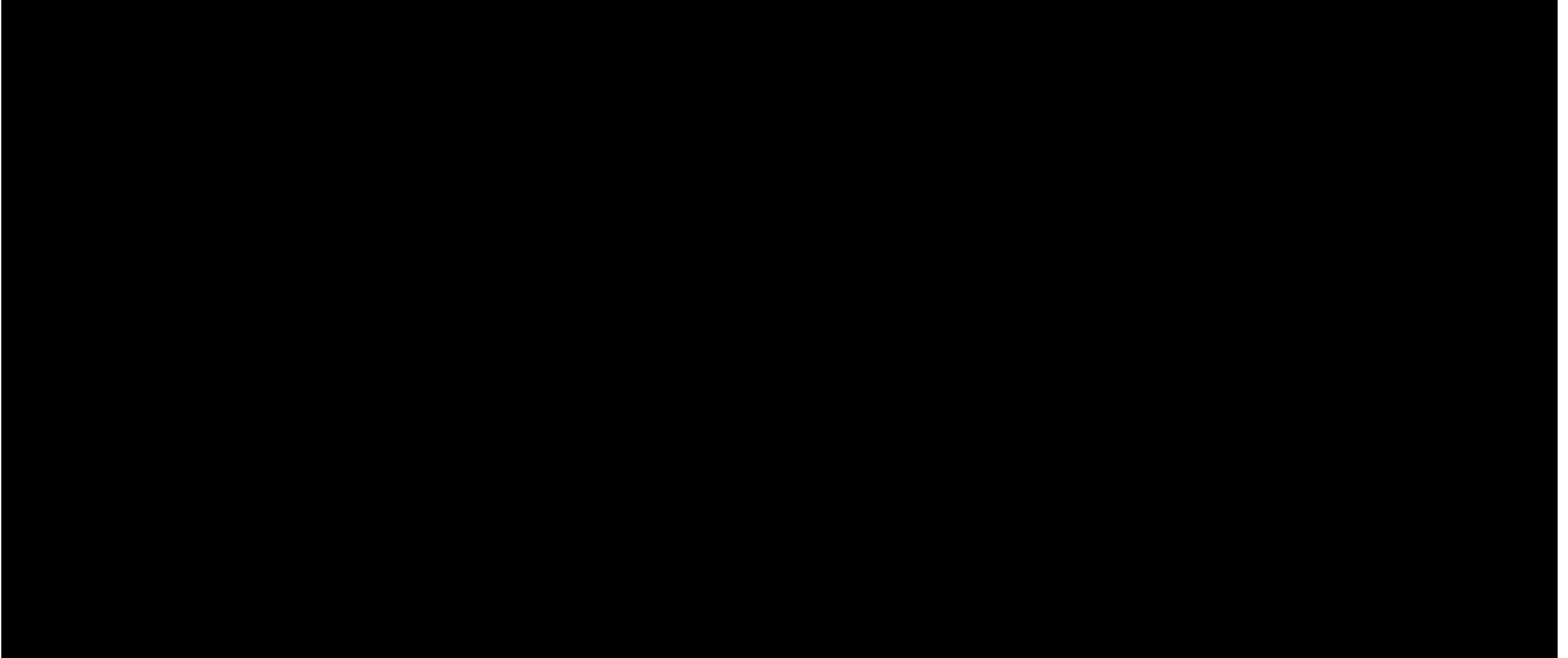
Root locus plot: different PSS and different scenarios (Monte Carlo)



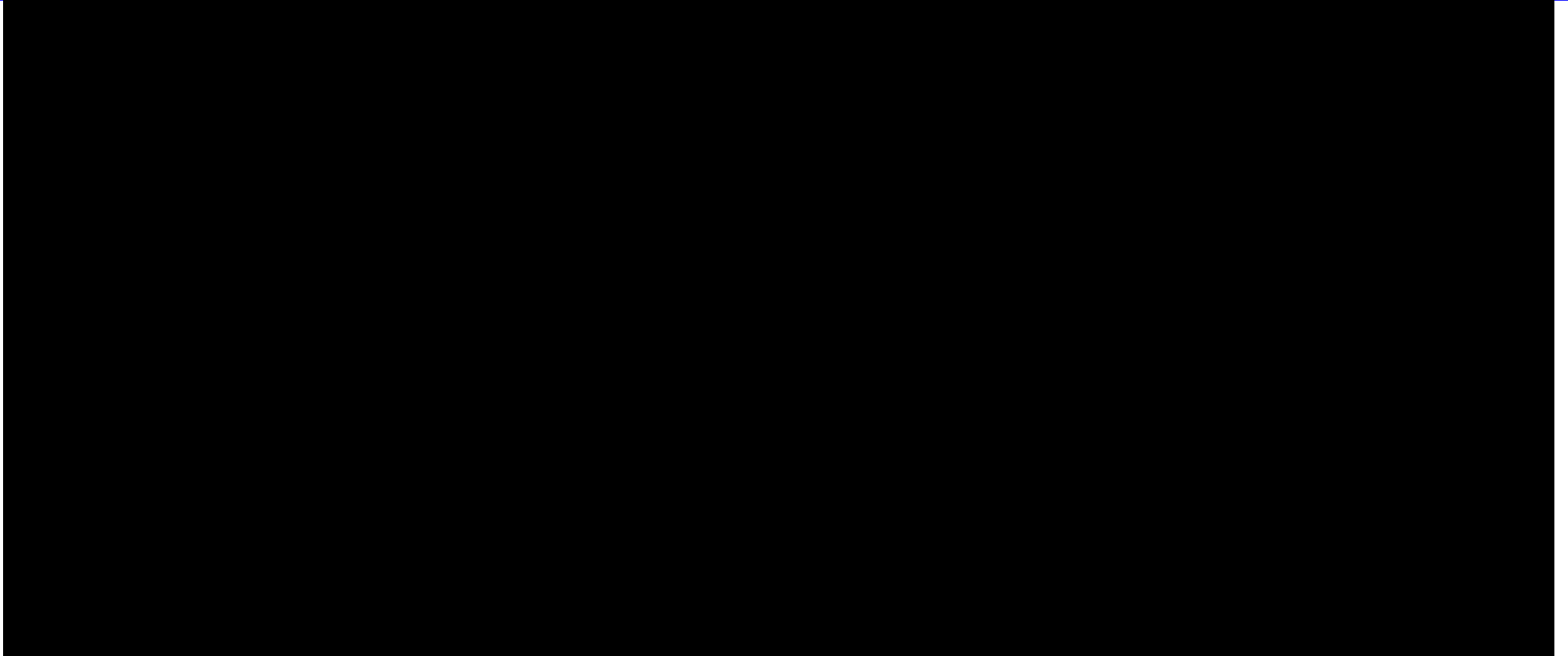
Local mode Oscillatory Stability Condition



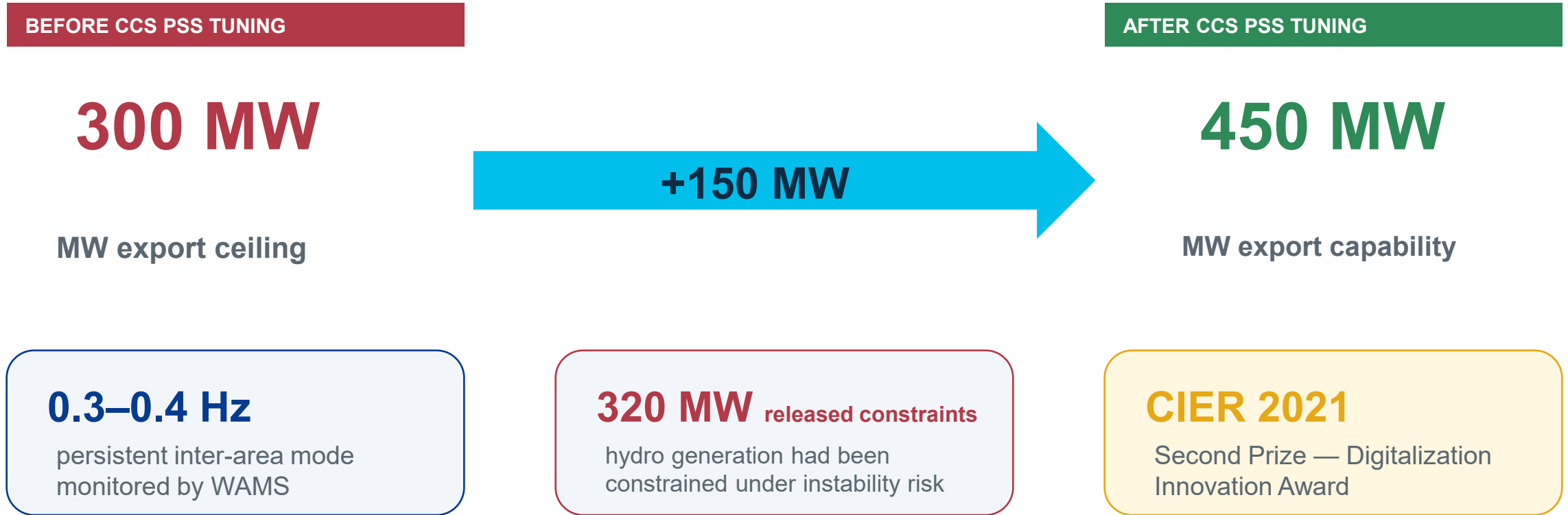
Testbed for PSS Tuning - CCS behaviour prior PSS Tuning



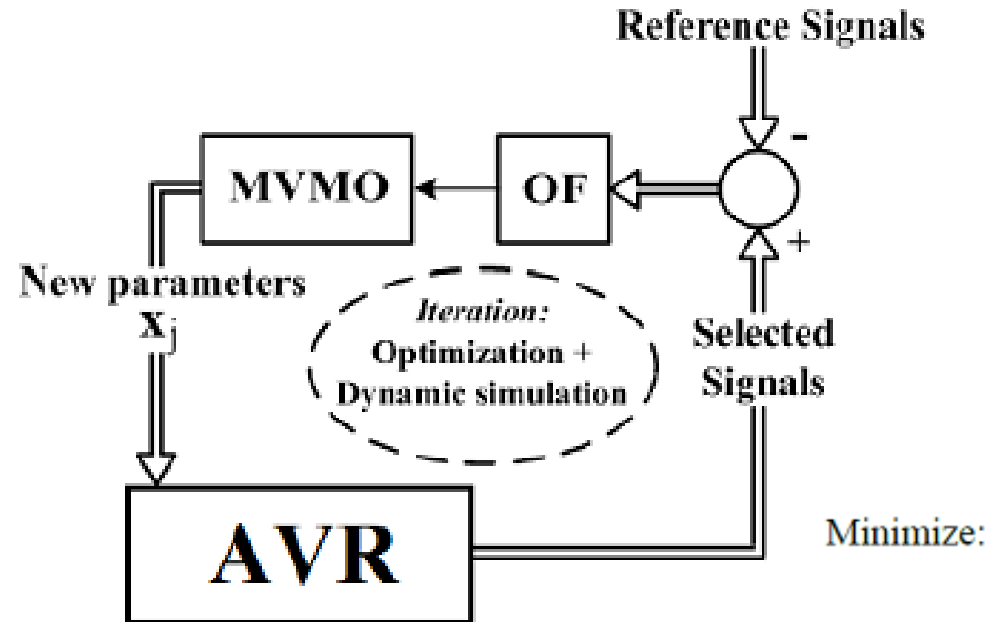
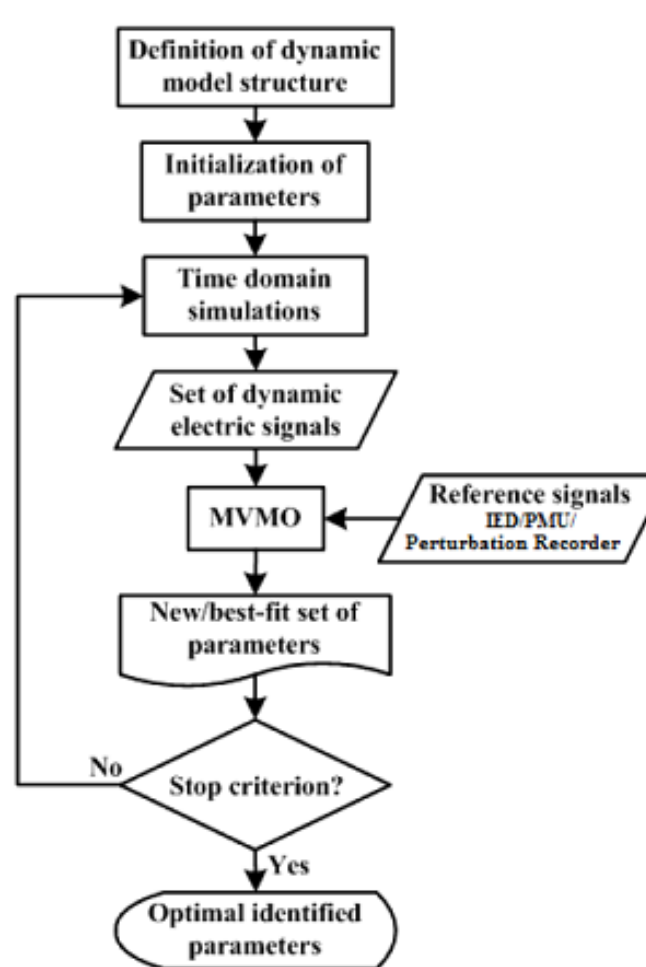
Testbed for PSS Tuning - CCS behaviour after PSS Tuning



PSS tuning improved damping and expanded secure export capability



Model Validation based on MVMO



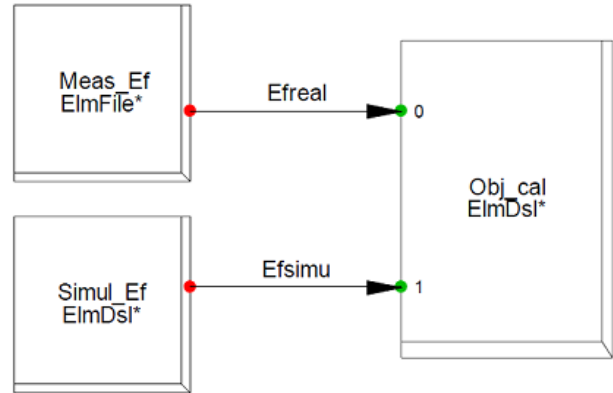
$$OF = \sum_{np=1}^p \alpha_{np} \int_0^{\tau} g(t) dt$$

$$g(t) = w_1 [y_1(t) - y_{1ref}(t)]^2 + \dots + w_n [y_n(t) - y_{nref}(t)]^2$$

Subject to:

$$\mathbf{X}_{j-min} \leq \mathbf{X}_j \leq \mathbf{X}_{j-max}$$

DSL Modeling

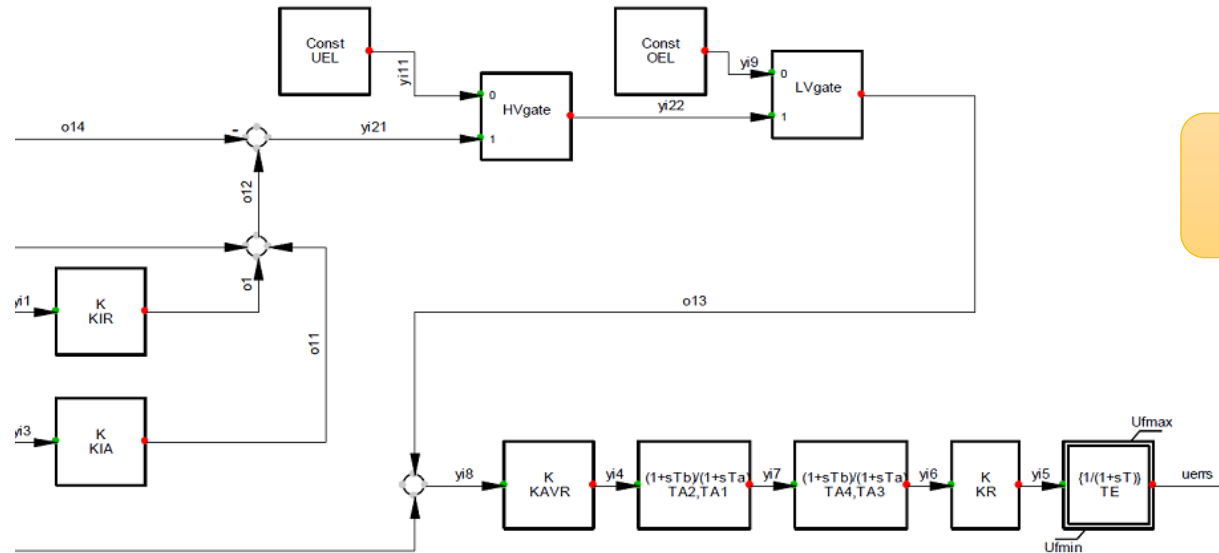


DSL

DPL

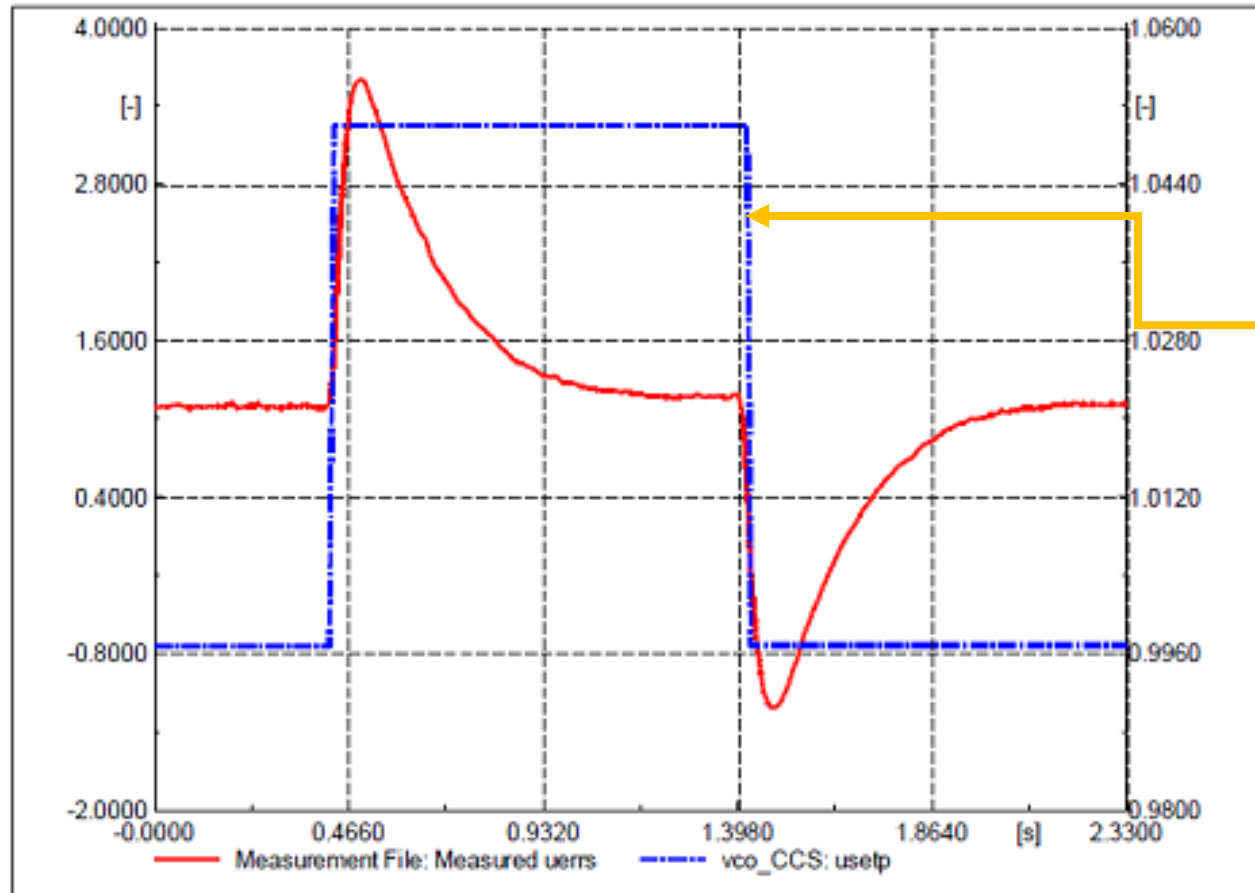
$$g(t) = w [Ef_{simu}(t) - Ef_{real}(t)]^2$$

$$\int_a^b f(x)dx \approx (b-a) \left[\frac{f(a) + f(b)}{2} \right]$$

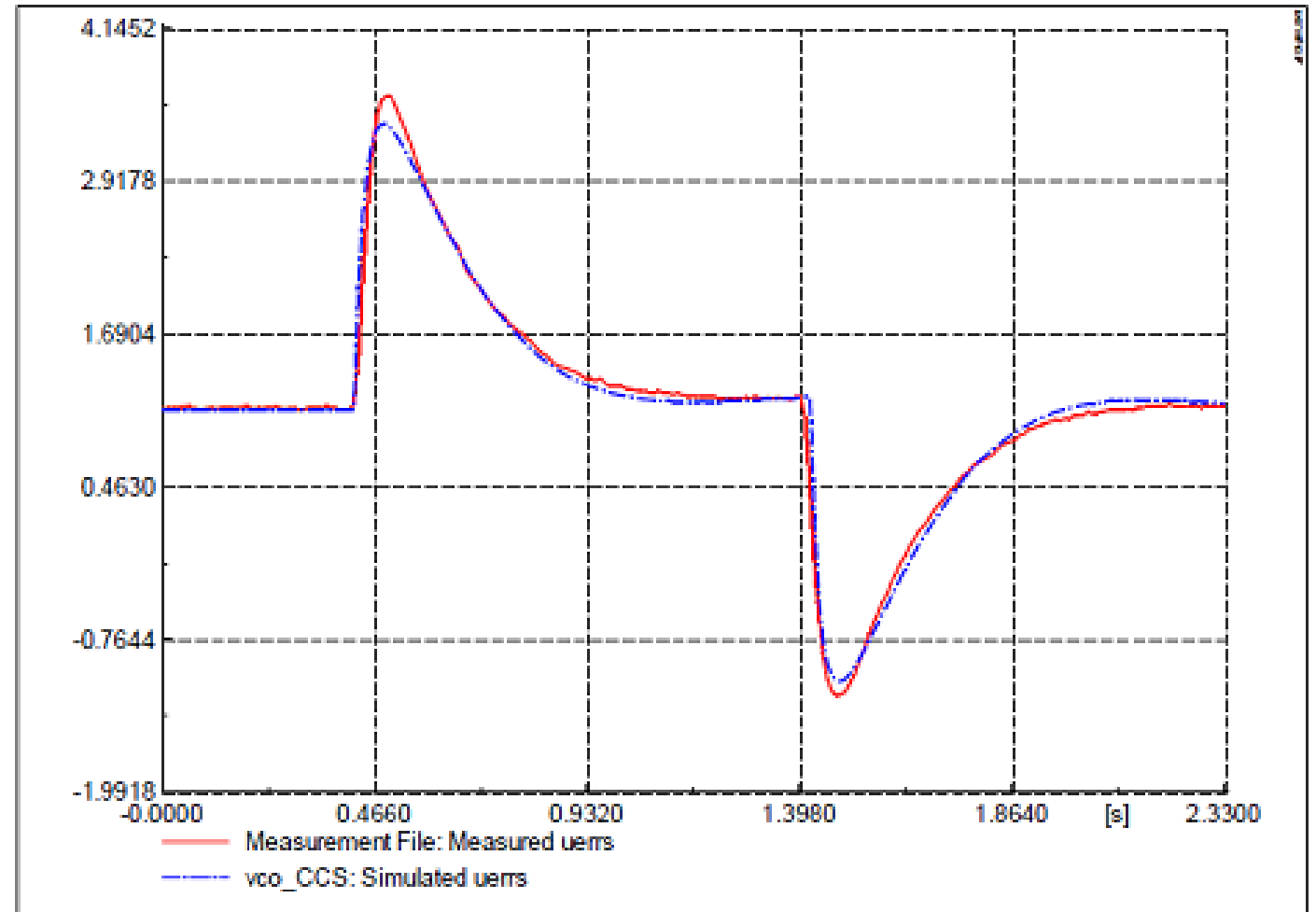
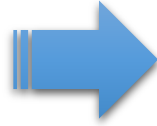
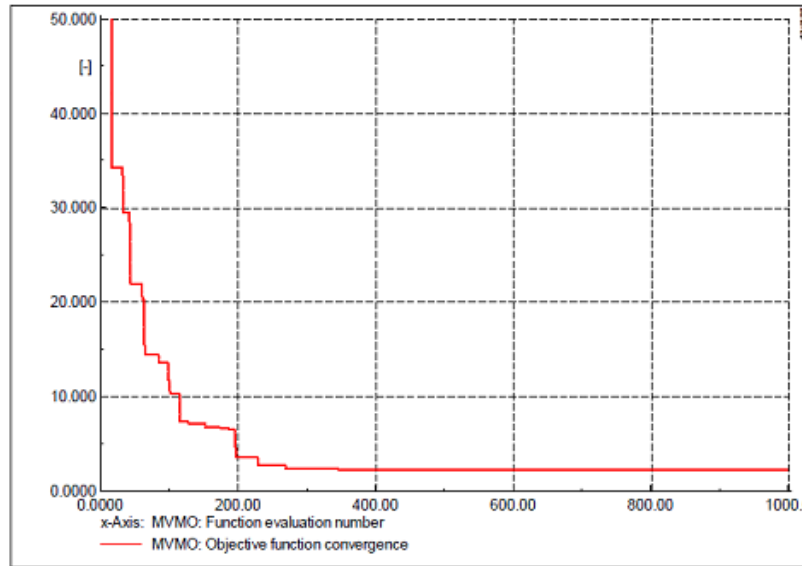


AVR

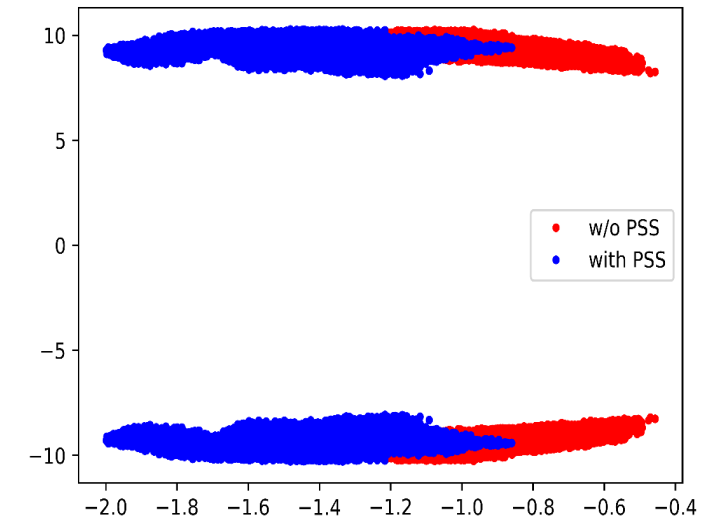
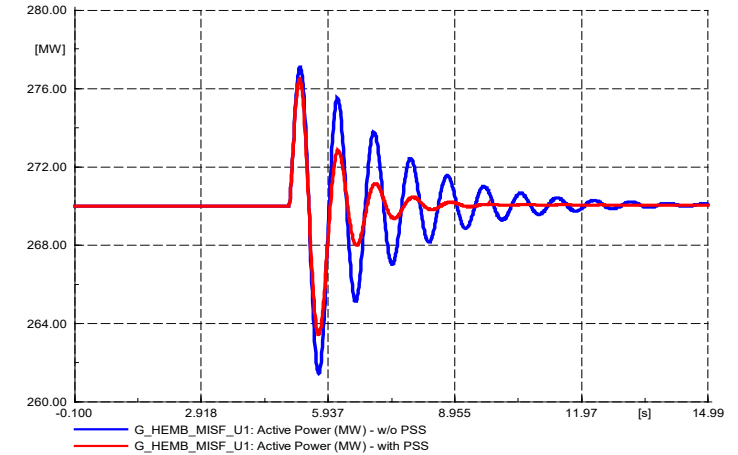
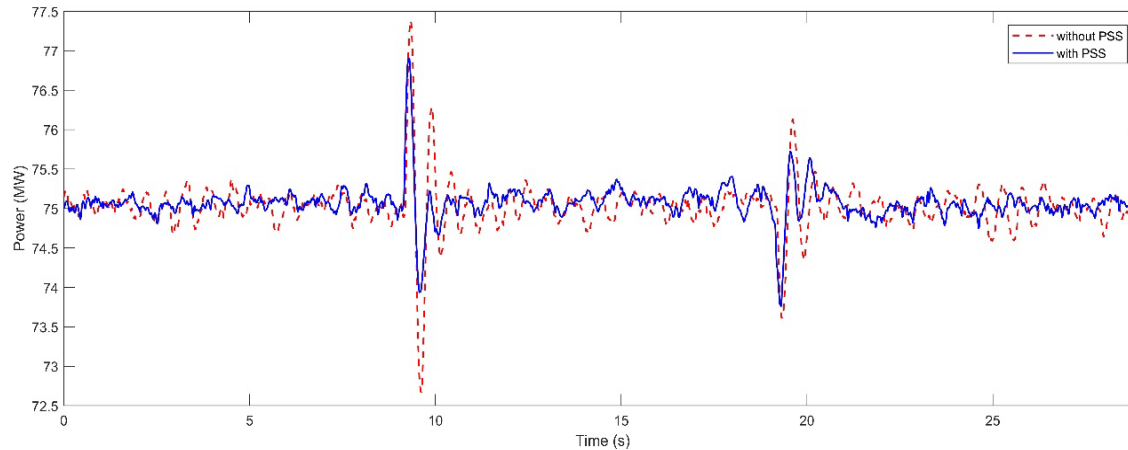
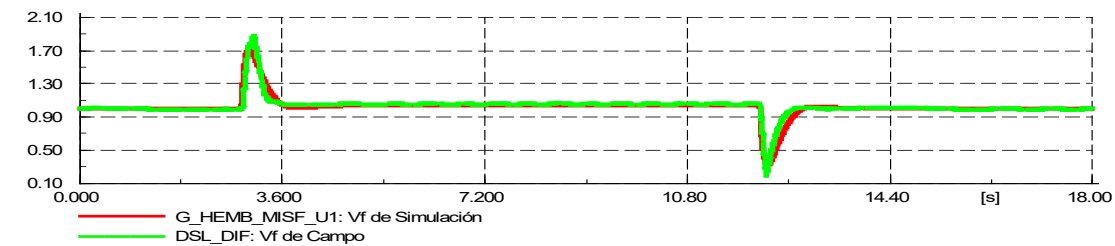
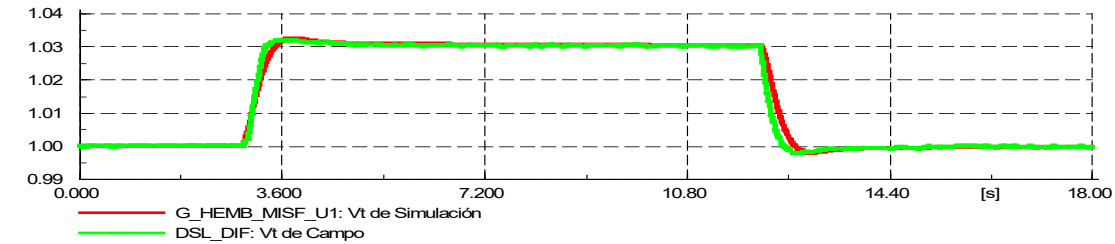
Parameter estimation



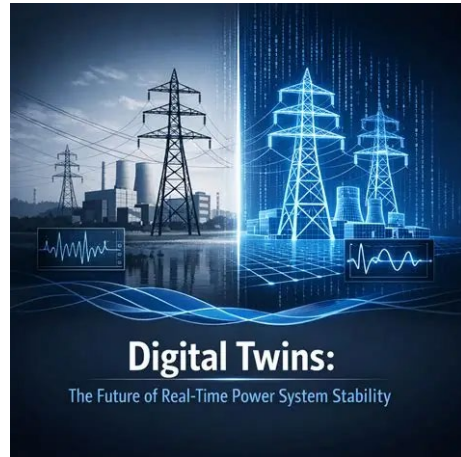
Parameter estimation



Ensuring the success of stability studies and other dynamic analysis



Real-time applications convert stability indicators into operator action



ANGLE

Phase-angle difference

VOLTAGE

Transmission-corridor margin

OSCILLATIONS

Mode frequency and damping

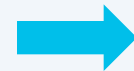
EARLY WARNING

Recognize stress
select control action
protect system integrity

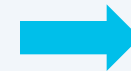


DIGITAL-TWIN TRAINING

PowerFactory static model



OpenModelica FMUs +
ePHASORsim

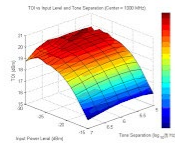


Virtual PMUs → WAProtector
HMI

Operators rehearse realistic dynamic scenarios using the same monitoring interface used in the control room.

SNI Digital Twin

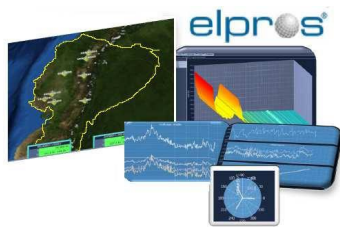
DSA



HYPERSIM

Real-Time Digital Simulator

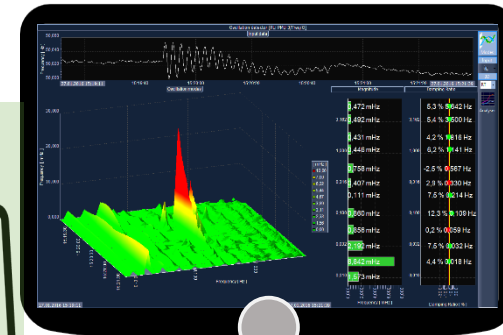
Virtual PMU
C37.118



Wide Area Monitoring System

- WAMS' APPLICATIONS
- - Angular Difference
- - Oscillatory Stability
- - Voltage Stability of Transmission
- Corridors
- - Frequency Monitoring

- Dynamic Simulation (Operation Commands)
- Load Flow Simulation



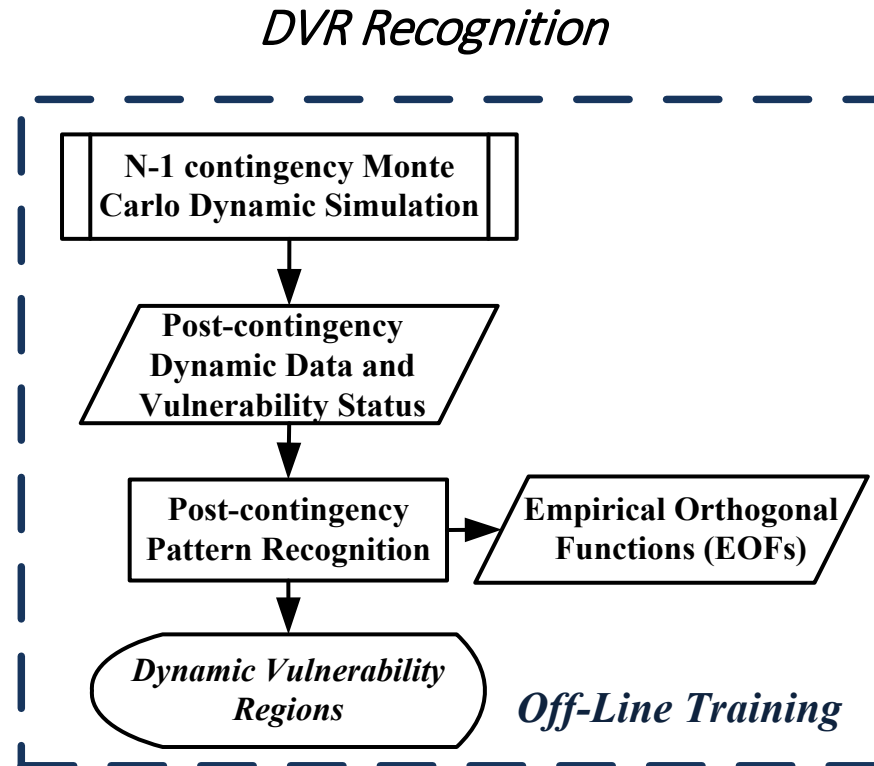
- Study Cases
- Generation and Demand



Training Environment

Machine learning improves early warning of SNI

Post-contingency Dynamic Vulnerability Region (DVR) $\Rightarrow$ DVA
 $\Rightarrow$ "Determine if the post-contingency dynamic state is within a "vulnerable" or "non-vulnerable" region"

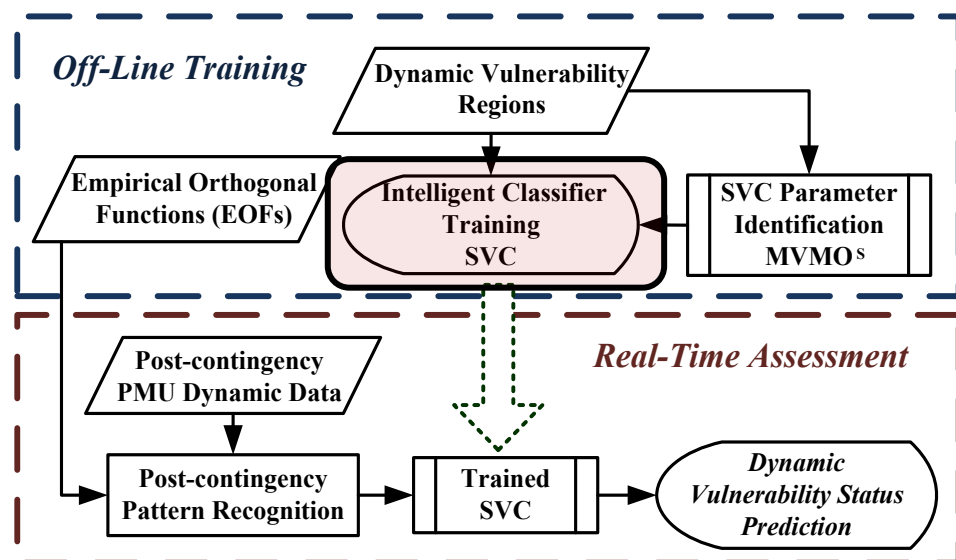


$$\mathbf{f}_k = \lambda_1^{1/2} u_{k1} \mathbf{v}_1 + \lambda_2^{1/2} u_{k2} \mathbf{v}_2 + \dots + \lambda_p^{1/2} u_{kp} \mathbf{v}_p$$

$$EV_i = \frac{\lambda_i}{\sum_{i=1}^p \lambda_i} \times 100$$

Machine learning improves early warning of SNI

Real-Time Status Prediction

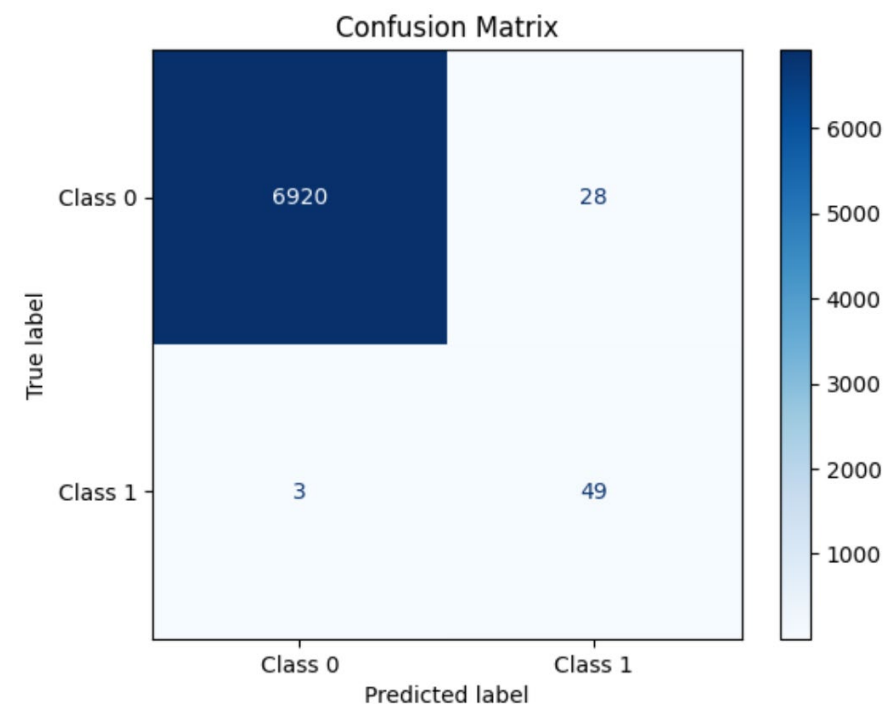


$$\min_{\mathbf{w}, b, \xi} \quad \frac{1}{2} \mathbf{w}^T \mathbf{w} + C \sum_{i=1}^l \xi_i \quad K(\mathbf{x}_i, \mathbf{x}_j) \equiv \phi(\mathbf{x}_i)^T \phi(\mathbf{x}_j)$$

$$\text{subject to} \quad y_i (\mathbf{w}^T \phi(\mathbf{x}_i) + b) \geq 1 - \xi_i, \quad K(\mathbf{x}_i, \mathbf{x}_j) = e^{-\gamma \|\mathbf{x}_i - \mathbf{x}_j\|^2}, \gamma > 0$$

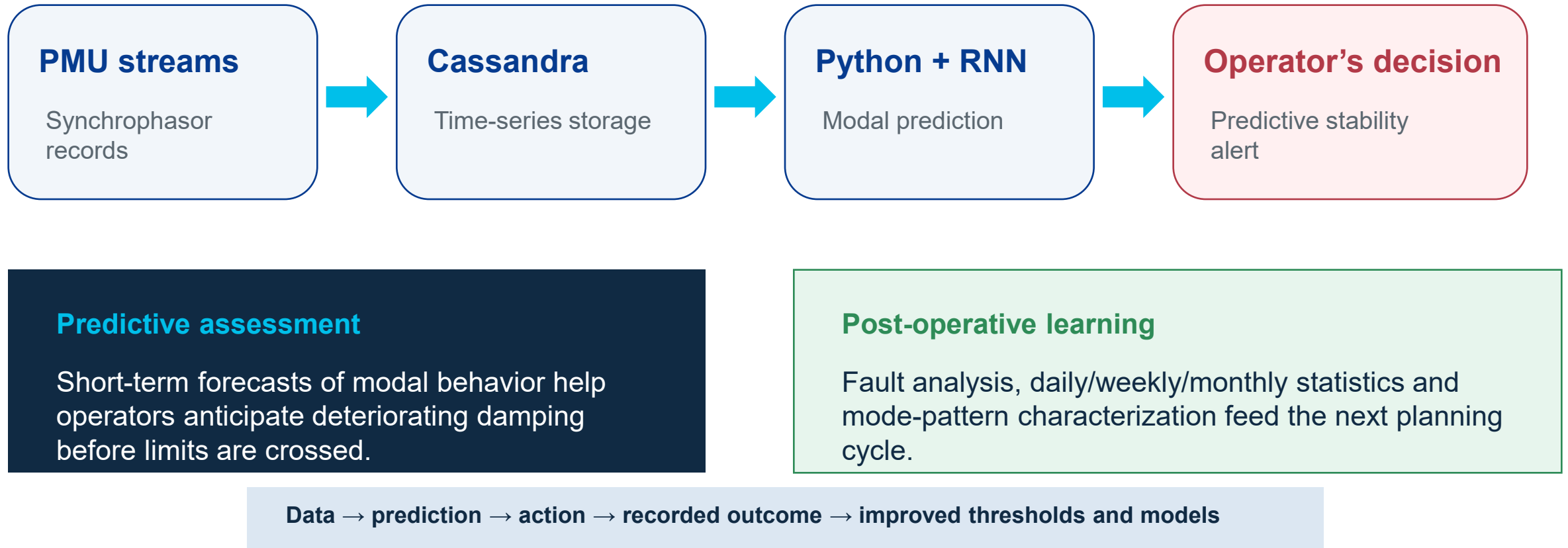
$$\xi_i \geq 0$$

52 of the 7000 Monte Carlo scenarios were transient unstable related to CCS

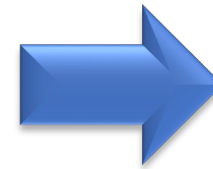
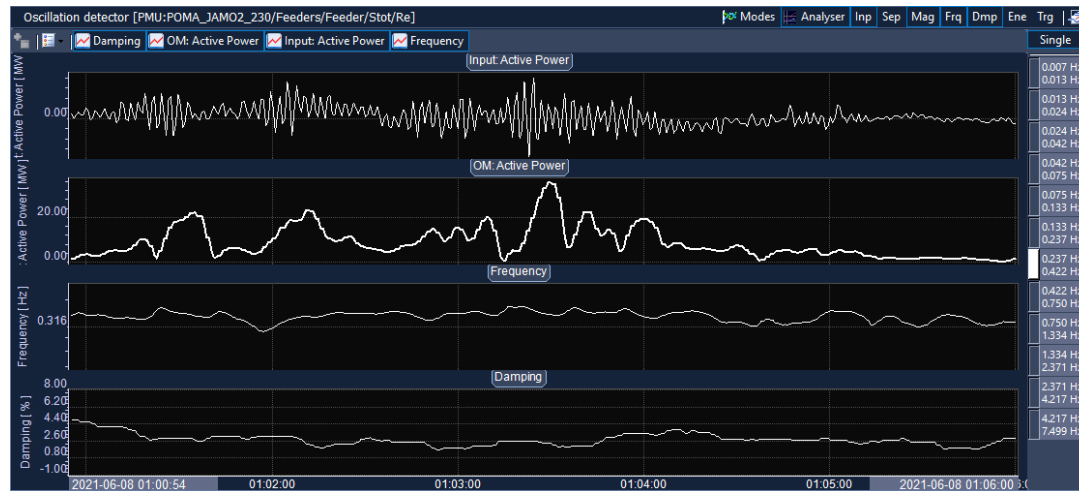


classification recall coefficient can be calculated of 0.996 for class 0 (stable) and 0.9423 for class 1 (unstable)

Streaming analytics with deep learning adds seconds-ahead prediction to the WAMS learning cycle



Early Warning – Oscillatory Stability: Deep Learning for Time Series Prediction - LSTM



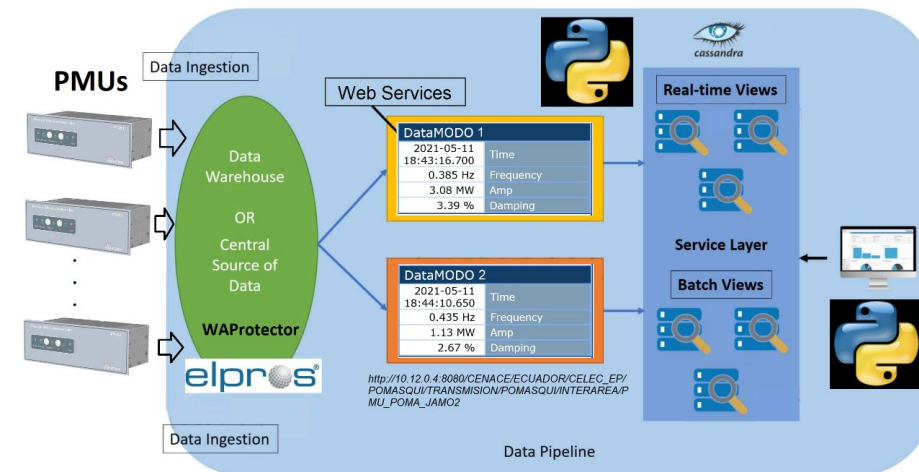
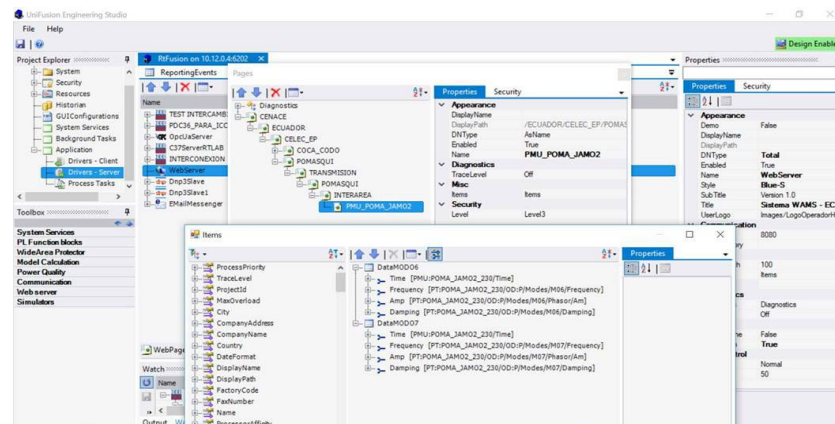
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Archivo Edición Ver Favoritos Herramientas Ayuda

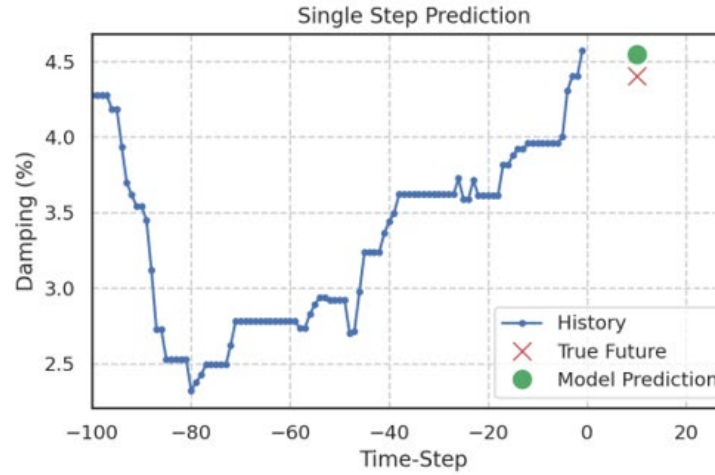
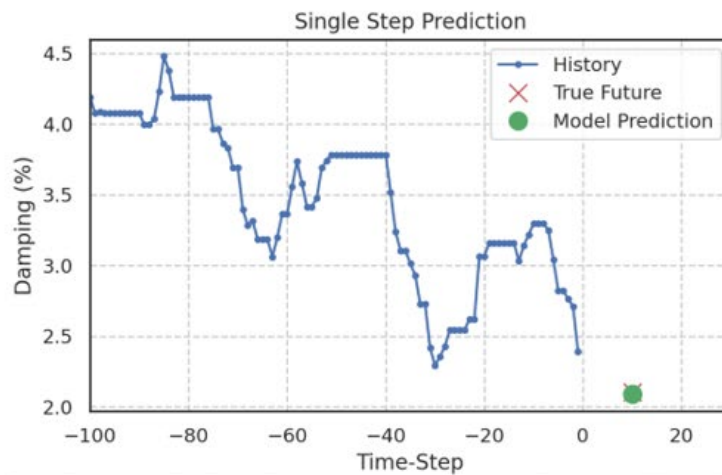
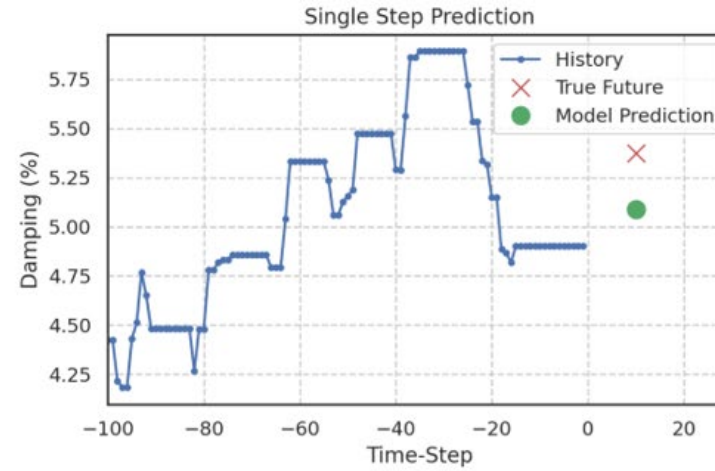
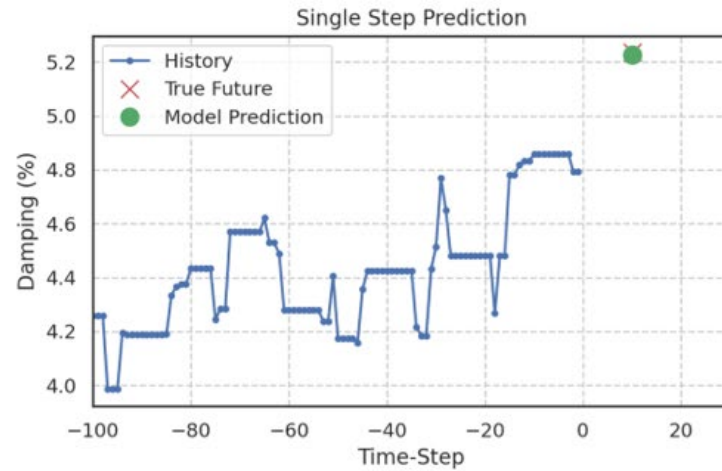
DataMODE 1	
2021-05-11 19:05:19.700	Time
0.370 Hz	Frequency
1.03 MW	Amp
4.00 %	Damping

DataMODE 2	
2021-05-11 19:05:19.700	Time
0.394 Hz	Frequency
0.18 MW	Amp
3.42 %	Damping

on-line =



Early Warning – Oscillatory Stability: Deep Learning for Time Series Prediction - LSTM



Conclusions: Operational impact and lessons learned

Dynamic observability enables secure operation

PMUs reveal stability phenomena that conventional monitoring cannot capture.

Measurements must lead improvement of power system operations

WAMS supports model validation, controller tuning, early warning and operating-limit definition.

Validated models allows simulation to deliver a real operational value → Controllers' tuning

Based on validated models, PSS retuning improved damping and increased secure Ecuador–Colombia export capability by 150 MW.

Digital twins enable a realistic dynamic security assessment

Real-time simulation and virtual PMUs connect engineering studies with operator training, field challenges and operational decision-making.

What is next? → From monitoring to prediction

The future operating paradigm is a continuous loop: **measure → validate → predict → act → learn.**

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